

Document Number DS406A

Description Dual Smart Charger Electronics

Inspired Energy Part Number CH4040

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Dual Smart Charger Specification

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1. **REVISION HISTORY**

Revision	Release	Revisions	Issued	Approved By
	Date		Ву	
1.0	4/12/16	First release	WRL	
2.0	3/14/18	Production Release	NCN	JAB,RAH,CR

2. INTRODUCTION

2.1. Scope

This specification describes the physical, functional and electrical characteristics of a dual smart Charger supplied by Inspired Energy. This specification is the interface document between Inspired Energy and its customers. It is understood that the customer may create their own internal specification. However, this specification is the master that defines the Charger's operation. The Charger produced will meet this specification.

2.2. Smart Charger Overview

This specification describes the physical, functional and electrical requirements for the CH4040 Dual Smart Charger assembly.

The CH4040 is capable of communicating with each of two batteries through separate System Management Bus (SMBus) communications and is fully SMBus Rev. 1.0, SBDS Rev. 1.1 and SCDS Rev. 1.1 compliant.

Redundant safety protection is provided by constant communications between each battery and the charger and by monitoring the battery on-board thermistor. In addition, the charger has passive over-current protection and active current monitoring of current to the battery as well as the current being sourced at its input.

2.3. General Precautions

2.3.1. Handling

- Avoid shorting.
- Do not immerse in water.
- Do not disassemble or deform.
- Avoid excessive physical shock or vibration.
- Never cover/block the fan exhaust or obstruct the airflow, as this will cause overheating.

2.3.2. Charge & Discharge

- Never use a charger or battery that appears to have suffered abuse.
- Only approved batteries should be charged/calibrated.
- Never use a modified or damaged battery or charger.
- Specified product use only.
- Caution during recalibration the battery connector and base of the charger will become warm.



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2.3.3. Storage

• Store in a cool, dry and well-ventilated area.

3. **REQUIREMENTS**

3.1. General Requirements

3.1.1. Input Power

The input power should comply with the following parameters: 24VDC, at least 60W.

3.1.2. Power-On-Reset

The LEDs will flash on 2 seconds at power up, for each of the two chargers.

3.1.3. Operation

Operational Temperature Limits: 0° C to $+50^{\circ}$ C, $\le 80\%$ RH

3.1.4. Storage

Storage Temperature Limits: -20° C to $+80^{\circ}$ C, $\le 80\%$ RH

The Smart Charger should be stored in an environment with low humidity, free from corrosive gas.

3.1.5. Terminal Specifications

J1 pin assignments (also refer to the mechanical drawing for additional details).

Terminal	Legend	Description
1	(+)	24V DC input.
2, 3	(-)	DC GND input.



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J3 (Secondary Battery) pin assignments (also refer to the mechanical drawing for additional details).

Terminal	Legend	Description	
1A,1B	(+)	DC Positive to battery1.	
2A,2B	(C)	SMBus Clock 1.	
3A,3B	(D)	SMBus Data 1.	
4A,4B	(THM)	Thermistor connection to battery 1.	
5A,5B	(-)	DC Negative to battery 1.	

J4 (Primary Battery) pin assignments (also refer to the mechanical drawing for additional details).

Terminal	Legend	Description
1A,1B	(+)	DC Positive to battery 2.
2A,2B	(C)	SMBus Clock 2.
3A,3B	(D)	SMBus Data 2.
4A,4B	(THM)	Thermistor connection to battery 2.
5A,5B	(-)	DC Negative to battery 2.

The SMBus Clock and data lines will be pulled up by the charger to a nominal 5V Vdd. Typically a $15K\Omega$ pull-up resistor is used, but please refer to the SMBus Specification for additional information.

3.2. Charger Electronics

3.2.1. Overview of Operation

The Smart Charger is capable of providing all auxiliary battery functions needed to recharge one or two Smart Batteries.

The charger is capable of communicating with each battery independently through the System Management Bus (SMBus). The charger is fully SMBus Revision 1.0 and SBDS Revision 1.1 compliant. The charger is implemented as a SBS compliant system.

An 8-bit Reduced Instruction Set CPU (RISC) is used to process the core algorithms and perform operations required for battery monitoring, charge/calibration control and user display.

Pertinent battery parameters are constantly monitored through out the charge/calibration cycle to insure safe and reliable operation. The battery thermistor is monitored as an independent and redundant safety monitor. SMBus Alarms are monitored and acted upon as defined in the Smart Charger Data Specification (SCDS).

The user is notified of operational mode and fault conditions by the on-board LEDs.



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3.2.2. DC Specifications

Parameter	Limits	Remarks
Active current consumption	<20mA	24V input power is applied.
Battery leakage current consumption	<40uA	Parasitic leakage current from each battery when
		input power has been removed from the charger.

3.2.3. Charging

During charge, for each battery the charger reads the battery status, battery mode, requested battery current, requested battery voltage, and battery temp. The requested battery voltage and current are then passed on to the charge control chip which has been configured to deliver up to 16.8 volts and 4 amps. The specified voltage and current of the battery read from the battery every second is then relayed to the charge control chip. Normal charge termination occurs when the battery reaches full charge and begins requesting 0 current and issues the TERMINATE_CHARGE_ALARM Warning.

Once fully charged, if a battery is left in the charger, the charger will re-initiate charge as requested by the battery. Typically, the battery will either request a trickle current, or else will begin requesting current following a predetermined amount of self-discharge.

The difference between the Primary and Secondary battery positions is that the Primary has priority, and will always charge at the maximum desired rate, drawing up to 60W from the input source. The Secondary position receives any excess current available from the input source (up to 60W) that the Primary does not require. If two batteries are started at the same time, the Primary battery will typically complete charging before the Secondary battery. The Primary battery slot is on the left as you face the front of the charger.

3.2.4. Regulation/Measurement Accuracy

3.2.4.1.Voltage

The charge voltage is measured and regulated to $\pm 0.8\%$ of the battery requested value.

3.2.4.2.Current

The charge current is measured and regulated to -14% to +6% or \pm 50mA of the battery requested value, whichever is greater.

3.2.5. LED Indication

The Charger provides LED display to inform the user of operation mode and fault conditions.

Off:	No Battery, or input voltage less than 18VDC
GREEN Flashing:	Charge in process
GREEN Solid:	Charge complete
RED:	Error
Error Conditions:	
Smart Charge:	Unsuccessful Charger communications within 210 second timeout.
Battery:	No Battery Communications within 20 second timeout.



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3.3. SMBus and SBDS Parameters

3.3.1. Overview of Operations

The Smart Charger is fitted with a microprocessor and associated circuitry for communication with the smart battery. Reference should be made to the following specifications when reading this section:

- System Management Bus Specification (Rev 1.0, Feb 15, 1995)
- Smart Battery Data Specification (Rev 1.1, Dec 11, 1998)
- Smart Battery Charger Specification (Rev 1.1, Dec 11, 1998)

3.3.2. SMBus Logic Levels

Symbol	Parameter	Limits		Units
		Min	Max	
Vil	Data/Clock input low voltage		1.5	V
Vih	Data/Clock input high voltage	3.5	5.5	V
Vol			0.4	V

3.3.3. Communication Protocol

SMBus Interface complies with System Management Bus Specification Version 1.0. The charger includes a simple bi-directional serial data interface. The charger processor uses the interface to access various battery pack registers.

3.3.4. Initialization Procedure

The interface uses a command-based protocol, where the charger processor sends the battery address command byte to the battery pack. The command directs the battery pack to either store the next data received to a register specified command byte or output the data specified by the command byte.

The Charger communicates with the battery pack using one of three protocols:

- Write Word
- Read Word
- Read Block

3.3.4.1.Write Word

The first byte of a Write Word access is the command code. The next two Bytes are the data to be written. In this example the master asserts the slave device address followed by the write bit. The device acknowledges and the master delivers the command code. The slave again acknowledges before the master sends the data word (low byte first). The slave acknowledges each byte according to the I²C specification, and the entire transaction is finished with a stop condition.





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3.3.4.2.Read Word

Reading data is slightly more complex than writing data. First the host must write a command to the slave device. Then it must follow that command with a repeated start condition to denote a read from that device's address. The slave then returns two bytes of data.

Note that there is not a stop condition before the repeated start condition, and that a "Not Acknowledge" signifies the end of the read transfer.



3.3.4.3.Block Read

The Block Read begins with a slave address and a write condition. Then it must follow that command with a repeated start condition to denote a read from that device's address. After the repeated start the slave issues a byte count that describes how many data bytes will follow in the message. If a slave had 20 bytes to send, the first byte would be the number 20 (14h), followed by the 20 bytes of data. The byte count may not be 0. A Block Read can transfer a maximum of 32 bytes.



3.3.5. Charger To Battery Message

The Charger acting in the role of a bus master, uses the read word, write word, and read block protocols to communicate with the battery, operating in slave mode.

Function	Command	Description		Access
	Code			
BatteryMode()	0x03	Battery Operational Modes.	Bit flags	r/w
Temperature()	0x08	Returns the pack's internal temperature.	0.1 ⁰K	r
Voltage()	0x09	Returns the battery's voltage (measured at the cell stack)	mV	r
Current()	0x0a	Returns the current being supplied (or accepted) through the battery's terminals.	mA	r
RemainingCapacity()	0x0f	Returns the predicted remaining battery capacity.	mAh	r
FullChargeCapacity()	0x10	Returns the predicted battery capacity when fully charged.	mAh	r
AverageTimeToFull()	0x13	Returns the rolling average of the predicted remaining time until the battery reaches full charge.	minutes	r
ChargingCurrent()	0x14	Returns the battery's desired charging rate.	mA	r
ChargingVoltage()	0x15	Returns the battery's desired charging voltage.	mV	r
BatteryStatus()	0x16	Returns the battery's status word.	Bit flags	r
ManufacturerName()	0x20	Returns a character array containing the manufacture's name.	string	r
DeviceName()	0x21	Returns a character array that contains the battery's name.	string	r
DeviceChemistry()	0x22	Returns a character array that contains the battery's chemistry.	string	r
ManufacturerData()	0x23	Returns data specific to the manufacture.		r



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3.3.6. Battery to Charger Messages

The battery, acting in the role of a bus master, uses the write word protocol to communicate with the charger, operating in slave mode. If the CHARGER_MODE bit in BatteryMode() is clear, the Battery will broadcast Charger request information at <u>15-second intervals</u>.

Battery-to-Charger Messages

Function	Command Code	Description		Access
ChargingCurrent()	0x14	Sends the desired charging rate to the battery charger	mA	W
ChargingVoltage()	0x15	Sends the desired charging voltage to the battery charger	mV	W

3.3.7. Critical Messages

Whenever the Battery detects a critical condition, it takes the role of a bus master and sends AlarmWarning() message to the Charger. The Battery broadcasts the AlarmWarning() message at <u>10 second intervals</u> until the critical condition(s) has been corrected.

Battery Critical Messages

Function	Command Code	Description	Unit	Access
AlarmWarning()	0x16	This message is to the host and/or charger to notify them that one		W
		or more alarm conditions exist.	word	

Alarm Bit Definitions

Hex	Battery Status	Status	Definition
4000	TERMINATE_CHARGE_ALARM	ON	Set when the battery detects that one or more of its charging parameters are out of range.
		OFF	Cleared when the parameters fall back within range.
1000	OVER_TEMP_ALARM	ON	Set when the battery detects that its internal temperature is greater than allowed.
		OFF	Cleared when the battery temperature falls back within acceptable range.
800	TERMINATE_DISCHARGE_ALARM	ON	Set when the battery determines that it has supplied all the charge it can without being damaged.
		OFF	Cleared when the battery reaches a state-of-charge sufficient for it to once again safely supply power.

Status Bit Definitions

80	INITIALIZED	ON	Always
		OFF	
40	DISCHARGING	ON	Battery "Current()" is not positive
		OFF	Battery "Current()" is positive
20	FULLY_CHARGED	ON	Set when the battery determines that it has reached a full charge termination
			point.
		OFF	Cleared when the battery determines that it can be charged again.
10	FULLY_DISCHARGED	ON	Set when the battery determines that it has supplied all the energy it can.
		OFF	Cleared when Relative State Of Charge \geq 20%.



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3.4. Mechanical Specifications

3.4.1. Weight

Approximately 0.90 lbs. (0.41kg) for the charger, 0.65 lbs (0.30kg) for the 24VDC power supply brick.

3.4.2. Mating Connectors

The recommended battery mating connectors are AMP/TYCO 787615-1, 787614-1 and 787613-1.

The input barrel jack is 2.1mm x 5.5mm.

3.4.3. Date Code

A date code is stamped on the back of each charger. The format is in the form of an 8 digit alphanumeric code

	ZZ <u>YYWW</u>	XX	
Manufacturing site	_↑	↑	_Charger Revision
Manufacturing date	↑		

3.4.4. Mains Variants

To accommodate different mains systems, the following variants are available: CH40400A (US mains cord), CH4040E (European mains cord), CH4040U (UK mains cord) and CH4040X (no mains cord). The 24VDC power supply is rated 100-240VAC, 50-60Hz.



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3.5. Environmental/Safety Specifications

3.5.1. EMC and Safety

The Smart Charger has the following approvals and is labeled according:

- EMC Directive
- WEEE Directive
- RoHS2 Directive
- EU Regulation (EC)
- EN 55032
- EN 55024
- EN 50581
- FCC Title 47 CFR, Part 15 Class B

3.6. Reliability

3.6.1. Warranty

A high quality standard is maintained by Inspired Energy. All products are warranted against defects in workmanship, material and construction. The warranty period is one (1) year from the date of shipment from Inspired Energy.

3.7. Packaging

3.7.1. Single unit per carton